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Evolving Machine Morality Strategies through Multiagent Simulations

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Instilling Morality in Machines-Multiagent Experiments

David Burke | Systems Science Seminar | June 3, 2011





Robots are coming!

- In Japan, researchers anticipate that robot nurses will be the answer to demographic changes.
- iRobot builds various robots for bomb disposal, carrying payloads, gathering "situational awareness".
- Futurists like Ray Kurzweil predict "...we will have both the hardware and software to achieve humanlevel intelligence in a machine by 2029"

Huge Implications

- Increasingly sophisticated information processing leads to more judgment and decision-making; hence, more autonomy.
- Human beings anthropomorphize at the drop of a hat -yelling at cars & computers.
- Jesse Bering: "...we sometimes can't help but see intentions, desires, and beliefs in things that haven't even a smidgeon of a neural system."
- Result: we're dealing with them as moral agents -- they have beliefs, goals, responsibilities.
- How do you instill morality in a machine?

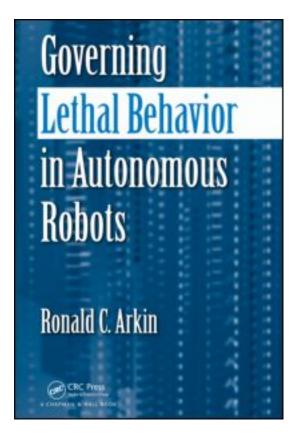
Didn't Isaac Asimov Solve This Problem Already?

Asimov's Laws of Robotics:

- 1. A robot may not injure a human being or, through inaction, allow a human being to come to harm.
- 2. A robot must obey any orders given to it by human beings, except where such orders would conflict with the First Law.
- 3. A robot must protect its own existence as long as such protection does not conflict with the First or Second Law.
- 0. A robot may not harm humanity, or, by inaction, allow humanity to come to harm.

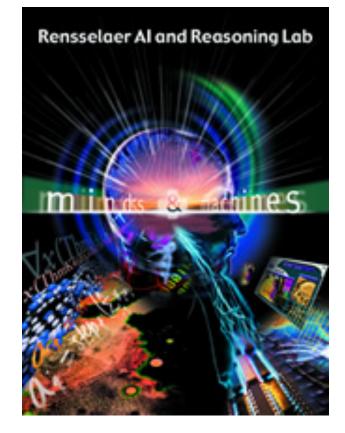
Ronald Arkin's Work

- *"Humane-oids* robots that can potentially perform more ethically in the battlefield than humans are capable of doing."
- Approach: codification of the Laws of War (LOW) and Rules of Engagement (ROE).



Logic-based approaches

- "A robot can flawlessly obey a 'moral' code of conduct and still be thoroughly, stupidly, catastrophically immoral."
- "...control robot behavior by fundamental ethical principles encoded in deontic logic..."



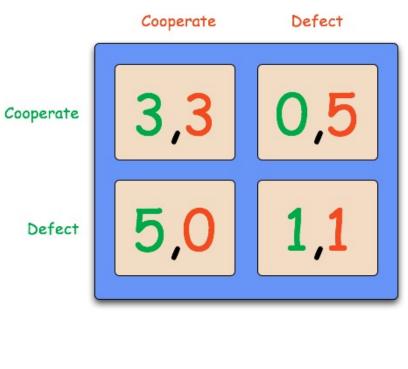
Moral Monocultures

- Fascinating Tradeoff:
 - perfect copying one of the defining characteristics of software
 - diversity ubiquitous strategy in biology
- Imagine the eventual large-scale successors to today's swarm robotics experiments -- do we want a 'moral monoculture'?
- My proposal: some kind of moral pluralism for autonomous systems.



Strategic interactions

- "The prisoner's dilemma is to game theorists what the fruit fly is to biologists"
- Many multiagent simulations & tournaments are based on this simple game.
- Idea: play the prisoner's dilemma (as well as other games) with a diverse population w.r.t. moral decision-making



Moral Foundations Theory

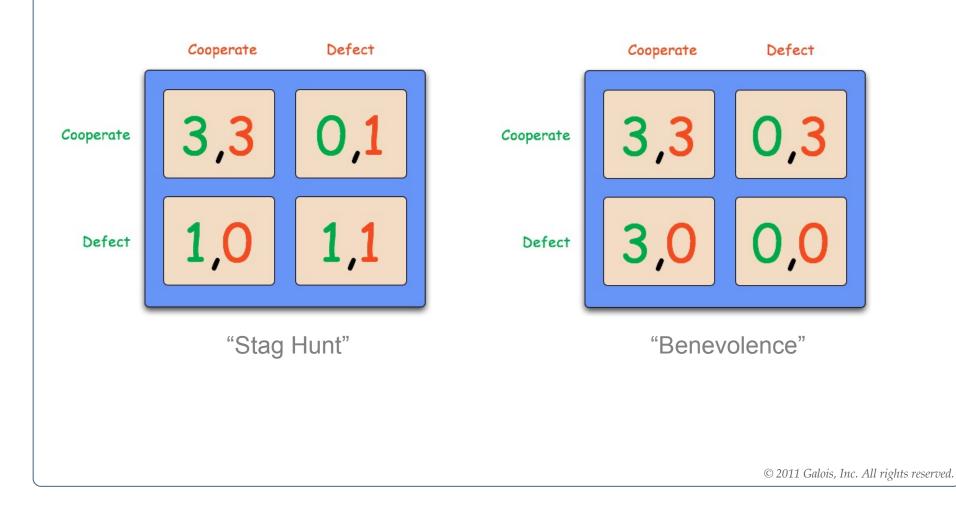
- 1. Reciprocity/Fairness
- 2. Harm/Care
- 3. Ingroup/Loyalty
- 4. Authority/Respect
- 5. Purity/Disgust

Are any of these attributes more foundational than the others?

Multiagent Simulation

- Implement a genetic algorithm:
 - Instantiate a starting set of agents with various strengths for the five moral attributes
 - For each attribute, we have a value, and a weighting.
 - Each agent also has an attribute ordering, and a decision style.
 - Let the agents interact; the successful ones breed
 - Watch the population evolve through the generations.
- The basic version of the simulation is ~600 lines of Python.

Other Strategic Interaction Games



Attributes

- each agent assigned to a 'tribe'
- 'decStyle'- first attribute vs. weighted (two weighting schemes)
- each attribute votes 'C' or 'D' (>= or < 0)</p>
- each attribute has a weight (0 to 1)
- 'recip' default, and choices for last round being 'CC', 'CD','DC','DD'
- 'harm' delta between agent scores
- 'auth' compare agent scores
- 'loyal' compare agent tribes
- 'disgust' agent1 checks to see if agent2's tribe is a member of agent1's disgust list.
- The 5 attributes are combined for a total (unless the decision style is 'first')

(very) Preliminary results

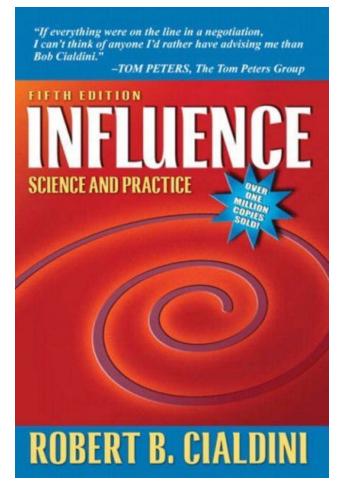
- Initial experiments featured five tribes, a population of 1000 agents, evolving over 250 generations, and runs for each of the three games.
- I had guessed that the "meaner" the game, the more we'd see traits like loyalty and authority dominate the population. (>80% of the population)
- Actual results: reciprocity and loyalty generally dominated the runs, but the "meaner" the game, the more likely that reciprocity came out ahead.
- More often than not, "first" decision-making outweighed "weighted" decision styles.
- A higher percent culled speeds up convergence, but doesn't appear to affect the shape of the final landscape.

Playing with the model

- Number of tribes; number of agents; number of generations
- Topology of contacts
 - random
 - local
 - movement allowed each generation
- Percentage culled with each generation
- What about cultural transmission? Accounting for cultural influence during a lifetime - right now, the agents don't learn from experience.
- How can we make the model more endogenous?

Making the model endogenous: Social Influence

- Six keys to influence:
 - Reciprocity
 - Commitment & Consistency
 - Social Proof
 - Authority
 - Liking
 - Scarcity
- Add costs to these efforts



Empathy

- Prosociality of human beings
- Some versions of empathy:
 - Knowing somebody's else's thoughts or feelings
 - Coming to feel as another person feels
 - Imagining how another person is thinking and feeling
 - Feeling distress at somebody else's suffering
- Computational Empathy -- true empathy vs. "as if" empathy

Selected Links

- Ronald Arkin
 - Home page: http://www.cc.gatech.edu/aimosaic/faculty/arkin/
- Selmer Bringsjord (RAIR lab)
 - Home page: http://www.rpi.edu/~brings/
 - A video of his talk on this subject: http://www.vimeo.com/4032291
- Jonathan Haidt
 - Home page: http://people.virginia.edu/~jdh6n/
 - Moral foundations page: http://faculty.virginia.edu/haidtlab/mft/index.php

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