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Abstract

Logic synthesis for reversible logic differs considerably from standard logic synthesis. The gates are multi-output and the unutilized outputs from these gates are called “*garbage*”. One of the synthesis tasks is to reduce the number of garbage signals. Previous approaches to reversible logic synthesis minimized either only the garbage or (predominantly) the number of gates. Here we present for the first time a method that minimizes concurrently the number of gates, their total delay and the total garbage. Our method adopts for reversible logic many ideas developed previously for standard logic synthesis (such as Ashenhurst/Curtis Decomposition, Dietmeyer’s Composition, non-linear preprocessing for BDDs), methods created in Reed-Muller Logic (such as Pseudo-Kronecker Decision Diagrams with Complemented Edges, Pseudo-Kronecker Lattice Diagrams and their generalizations) and introduces also new methods specific to reversible logic.

1. Introduction

Reversible logic.

Reversible are circuits (gates) in which the number of inputs is equal to the number of outputs and there is a one-to-one mapping between vectors of inputs and outputs; thus the vector of input states can be always reconstructed from the vector of output states. A gate with k inputs and k outputs is called a $k*k$ gate. All gates in a reversible circuit have to be reversible. A circuit is ***conservative*** when it preserves the numbers of all logic values in each input-output pair. A ***balanced function*** has half of minterms with value 1 and half with value 0. A circuit without constants on inputs, which includes only reversible gates, realizes on all outputs only balanced functions. Therefore, ***garbage*** outputs are necessary in order to realize non-balanced functions. There are reversible circuits (such as Fredkin gate) that are conservative, but most such circuits are not conservative (for instance Toffoli gate is not conservative). Similarly, not all conservative gates are reversible. Additional constraint of reversible logic is that the fanout of every signal, including primary inputs, must be one. The graph of the reversible circuit must be a DAG (Directed Acyclic Graphs), which means - there can be no any loops of gates or internal loops in a gate.

Motivation to study reversible logic.

As proved by Landauer [45], using traditional irreversible logic gates such as AND or multiplexer leads inevitably to energy dissipation in a circuit, regardless of the realization of the circuit. Bennett [4] showed that for power not to be dissipated in an arbitrary circuit, it is necessary that this circuit be built from ***reversible gates***. Power loss due to irreversible gates is negligible for current logic technologies, therefore other methods of low power design are still predominantly researched. However, if the Moore’s Law will continue to be in effect, energy losses due to non-reversible design would become essential in 2020 or earlier. Moreover, quantum logic is reversible, and the problem of searching for efficient designs of quantum circuits [16] includes as its sub-problem the problem of synthesis using classical reversible gates, being the topic of this paper. Many of the methods presented here in formulation for classical logic, can be, however, adapted to quantum logic as well, because reversibility is its most significant property from the gate composition point of view. Of course, Bennett’s theorem is only a necessary and not sufficient condition. Its extreme importance lies in the technological necessity that ***every future technology will have to use reversible gates in order to reduce power***. Therefore, the results presented here will be useful for ***arbitrary*** reversible technology, not only quantum, but also CMOS, DNA, optical [57], etc.

The problem we want to solve.

The goal of this paper is to develop a methodology to synthesize binary combinational reversible logic circuits in regular and non-regular structures, in binary logic, for multi-output functions, and minimizing a complex cost function. **This function is a weighted sum of the number of garbage outputs, the number of levels of the circuit, and the number of gates.** Such problem has never been formulated in the past, to the best of our knowledge. Our method will be only approximate, but at least we attempt to formulate a realistic synthesis problem in contrast to the previous research. We will assume that the program disposes a library of reversible 3×3 gates (cells), each of them with an area cost and a delay cost. Arbitrary number of constants 0 and 1 is available. The weights in the cost function should be selected for each technology separately, for instance, garbage, related to the size of qubit register, is absolutely critical for current quantum technology, but number of levels may be more important for CMOS reversible/adiabatic circuits.

Previous work on reversible logic synthesis.

In the seminal paper [29], Fredkin and Toffoli formulated the problem of reversible logic synthesis. They also showed examples, illustrating why classical logic synthesis methods cannot be directly applied to design of reversible circuits. They did not, however, present any cost function or synthesis method, nor did they give any hints how such goals can be achieved.

Surprisingly little have been published since then on logic synthesis algorithms for reversible logic. The universality of sets of 3×3 conservative gates with respect to all 3×3 conservative circuits was considered for cascades by Sasao and Kinoshita [67]. They also proved in [68] that an arbitrary n -variable Boolean function can be implemented by $(n+3) \times (n+3)$ circuits using 3×3 Fredkin gates (which they called P elements). Lemma 4.3 of [68] shows that an arbitrary logic function can be realized with three input constants and some P elements. The feature of this realization is that it produces a small garbage. Unfortunately, their approach leads to long (of the order of 2^n) cascades of gates. Such cascades are thus slow and expensive. The method is also not general as it assumes design using a limited set of reversible gates, namely Fredkin gates. There is no argument in reversible technologies to restrict the gates to only Fredkin, or even only conservative reversible gates. Moreover, the cascade structure considered by Sasao is quite restricted and no constructive method was shown to synthesize an arbitrary function using Fredkin gates. The method was for single-output functions only. Despite these weaknesses, the paper of Sasao and Kinoshita is important as a first paper on reversible logic synthesis, that proposed to use cascades. A paper by Storme et al. [71] analyzed the group theoretic properties of all 3×3 reversible functions and found the classes of most powerful gates. An interesting result of this paper is that every 3×3 reversible function can be realized by a cascade of some cells (3×3 functions) found in [71], and the libraries of small subsets of complete gates were proposed based on counting results. These libraries have 3×3 reversible gates that are “most powerful” as able to create all 3×3 functions with shortest cascades. Similar results (without negations) were obtained in [38]. The findings from [71,38,39,40,41] can be used to create libraries of cells, that can be next used with “technology matching” algorithms to select the best cell combination for a given 3×3 or 4×4 reversible function. The advantage of this approach is that equivalence classes with respect to signal permutations, negations, and linear transformations were also considered. Thus the results of this paper allow for more realistic and optimal synthesis of 3×3 and small $k \times k$ circuits than the results of Sasao and Kinoshita. Observe that the results are for 3-output functions rather than for single-output functions. However, the constructive method for synthesis was not given, as the paper was based on exhaustive analysis using algebraic software for group theory.

In contrast, several approaches to reversible logic synthesis proposed by Picton [57,58,59,60] attempt to minimize the number of gates, but produce very large garbage and usually also delay. In our previous papers [54,55,56] we proposed several methods aimed at simultaneous minimization of the number of gates, delay and garbage, but some of these methods give high quality results mainly for symmetric functions [55,56]. Other methods assumed leveled realizations (such as modified decision diagrams and lattices [54]) which can also lead to designs with high garbage for some functions. Therefore, we continued to work towards really general synthesis methods for reversible logic that would be counterparts of the well-known synthesis methods based on functional decompositions in standard binary logic. Each new method that we developed was subsequently compared on small functions with previous methods to understand better its advantages and disadvantages. A general reversible logic synthesis problem is difficult and we concentrate first on finding high quality solutions for rather small functions. Some of our approaches work also for very large functions, but their quality is sacrificed.

The result of this paper.

Here we introduce a ***general method of hierarchical decomposition*** of arbitrary reversible functions into ***arbitrary*** reversible logic gates. If the original function is not reversible, it is completed to a reversible function either in the preprocessing stage or during the decomposition (section 5), by adding additional constant input signals and garbage outputs. To distinguish this new general decomposition from the well-known functional decomposition approaches of Shannon, Ashenhurst and Curtis we call it the ***Multi-purpose Portland Decomposition***, the ***MP-decomposition*** for short. In contrast to the previously published papers, the ***MP-decomposition*** can use arbitrary number of ***arbitrary types of reversible gates*** at the same time. It is also not restricted

to certain decomposition structures, e.g. regular lattices. This decomposition has *four types* and *two modes*. Each type can be executed in one of two modes: *forward mode* and *backward mode*. The decomposition types are *output decomposition*, *input decomposition* and *Curtis decomposition*. The forward mode means that the processing is performed on the original reversible function, the backward mode means that the processing is performed on a function that is a reverse of the original function (see section 5). While the output decomposition is new, the input composition and the Curtis decomposition types are adaptations of standard binary logic decompositions to reversible binary logic.

Additional remarks.

This is a *general overview paper* and an introduction to reversible logic synthesis research performed by our group. For simplicity of explanation, we resigned from presenting formally the representations, formulas, algorithms and data structures. Instead, we have concentrated on the main ideas useful to create synthesis methods for reversible logic, in order to outline the general issues related to selecting reversible gates, creating network structures, and synthesis approaches. For instance, we illustrate all the methods using Karnaugh maps, but the software that we are going to develop will use BDDs to represent all data involved in reversible logic: ON and OFF sets of values, characteristic functions for functions and relations, SPFDs, and representation of gates as binary vector permutations and matrices. To improve the tutorial value of the paper, a complete list of references is given. However, knowing all details presented in them is not necessary for understanding of our paper.

2. Binary Reversible Gates

Many universal reversible gates have been considered (see [18,38,39,40,41,71]), here only some of them will be used. There exists only one 1*1 gate, which is an inverter (we do not count a wire as a gate). This gate is very important since it does not introduce garbage outputs. Thus the representation and synthesis methods should allow to use inverters in intermediate representations whenever possible; like for instance using decision diagrams (DDs) with complemented edges rather than standard DDs. There are several 2*2 gates in reversible logic and they are all linear. A gate is linear when all its outputs are linear functions of input variables. Let *A*, *B*, and *C* be inputs and *P*, *Q* and *R* outputs of a gate. The 2*2 *Feynman gate*, (called also *controlled-not* or *quantum XOR*), realizes functions $P = A$, $Q = A \oplus B$, where operator \oplus denotes EXOR.. When $A = 0$ then $Q = B$, when $A = 1$ then $Q = \neg B$. With $B=0$ the 2*2 Feynman gate is used as a *fan-out (or copying) gate*. Every linear reversible function can be built by composing only 2*2 Feynman gates and inverters. There exist $8! = 40,320$ 3*3 reversible logic gates, some of them with interesting properties, but here we are interested in synthesis methods using *arbitrary* reversible gates, so we will restrict ourselves to only few gate types. There exist two well-known universal 3*3 reversible gates: *Fredkin gate* [29] and *Toffoli gate* (also called 3*3 Feynman gate or Controlled-Controlled-not).

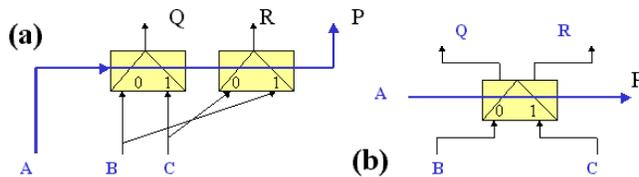


Figure 1. Notation for Fredkin Gate. (a) the circuit, (b) the simplified symbol of the gate

The 3*3 *Fredkin gate* is described by the following equations: $P = A$, $Q = \text{if } A \text{ then } C \text{ else } B$, $R = \text{if } A \text{ then } B \text{ else } C$. In terms of classical logic this gate is just two multiplexers controlled in a flipped (permuted) way from the same control input *A*. The circuit and the symbol notation for 3*3 Fredkin gate are shown in Figure 1. As we see, the 3*3 Fredkin gate is a permutation gate. It permutes the data inputs of its two multiplexers under control of the control input of these multiplexers. This control input is also an output from Fredkin gate. The fact that output *P* replicates input *A* is very useful because it allows to avoid fanout gates. This fact is used for instance to implement gates that correspond to the same level of a reversible decision diagram, lattice diagram or other leveled diagram, PLA-like circuits for SOP or ESOP and other regular structures

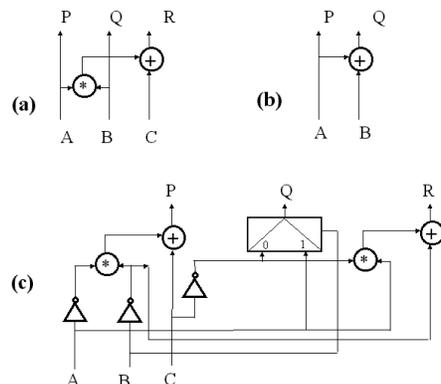


Figure 2. Possible realizations of Reversible gates. (a) Toffoli gate, (b) Feynman 2*2 gate, (c) Kerntopf gate.

of gates. The cells are just cascaded: output P goes to input A of the next cell at the same level (let us recall that fanout is not allowed in reversible logic). Fredkin gates are examples of what we define here as *one-through gates*, which means gates in which one input variable is also an output. The 3*3 Toffoli gate (Figure 2a) is described by these equations: $P = A$, $Q = B$, $R = AB \oplus C$, Toffoli gate is an example of *two-through gates*, because two of its inputs are given to the output.

The Kerntopf gate [38,56], Figure 2c, is described by equations: $P = 1 \oplus A \oplus B \oplus C \oplus AB$, $Q = 1 \oplus AB \oplus B \oplus C \oplus BC$, $R = 1 \oplus A \oplus B \oplus AC$. When $C=1$ then $P = A + B$, $Q = A * B$, $R = \neg B$, so *AND/OR* gate is realized on outputs P and Q with C as the controlling input value. When $C = 0$ then $P = \neg A * \neg B$, $Q = A + \neg B$, $R = A \oplus B$. Therefore for control input value 0 the gate realizes *NAND* and *IMPLICATION* on its outputs P and Q , respectively. As we see, the 3*3 Kerntopf gate is not a one-through nor a two-through gate.

Example 1. We will show that each output function realized by the Kerntopf gate belongs to the same NP equivalence class (negation/permutation of inputs) as Davio and Shannon expansion operators. (Positive Davio is used once in Toffoli gate and Shannon operator is used twice in Fredkin gate).

$$P = 1 \oplus A \oplus B \oplus C \oplus AB = A \oplus B \neg A \oplus C \oplus 1 = (A+B) \oplus \neg C = \neg A \neg B \oplus C = \text{Davio}(\neg A, \neg B, C),$$

$$Q = 1 \oplus AB \oplus B \oplus C \oplus BC = 1 \oplus AB \oplus (B+C) = AB \oplus \neg(B+C) = AB \oplus \neg B \neg C = \text{Shannon}(B, \neg C, A),$$

$$R = 1 \oplus A \oplus B \oplus AC = \neg B \oplus A \neg C = \text{Davio}(A, \neg C, \neg B).$$

Similar transformations can be performed on all H gates introduced in [38]. The functions in them belong also to linear class of 3 inputs. In particular, H gates include the gate called “Kerntopf gate” utilized in [56]. Because the negations can be included into gates, a set of standard cells with such negations inside the cells can be introduced. We will call them “extended standard cells”.

Let us assume that we have a technology in which permutations and negations are easily realizable. Every balanced function of not more than 3 variables belongs to one of six NPN equivalence classes. Their representatives are: (a) for one variable – variable (negation), (b) for two variables – EXOR, (c) for three variables - Davio, Shannon (multiplexer), EXOR, and majority operators. Therefore every 3*3 reversible gate is a combination of three out of six functions, possibly with permutations and/or negations of some inputs and negations of some outputs. The knowledge of this fact will help to build these gates in current or future technologies. In the technologies that we are aware of, both permutations and negations are relatively easy to obtain. The above characterization of reversible gates is also used in logic synthesis algorithms that apply these gates. Kerntopf gate [38] has a theoretical advantage of having more cofactors than other gates, thus being able to realize more subfunctions with some inputs set to constants. This property was used in [56] to design symmetric functions and regular structure of a reversible FPGA. Despite of this advantage of Kerntopf gate over classical Fredkin and Toffoli gates, so far there are no optical, quantum or CMOS realizations of this gate. We introduce this gate here for the reason of demonstrating the generality of our decompositional synthesis approach. It should be also noted that although the Kerntopf gate looks more complex for CMOS realization, it is not necessarily so for other realization technologies. Realization of 3*3 binary reversible gates using *2*2 and 1*1 unitary quantum gates* is discussed in [22]. Many cascades of length 5 realizing universal binary logic reversible gates have been shown using these quantum gates, therefore it seems likely that *every* universal 3*3 gate of reversible logic, including all Kerntopf’s H gates and Storme’s et al gates, would require 5 quantum gates.

3. Preprocessing

Because some of the presented below decompositions require complex data processing to find a high quality solution, large multi-output functions should be first partitioned to smaller functions. This is based on their representations such as Binary Decision Diagrams, Pseudo-Kronecker Decision Diagrams (PKDD) [23], Pseudo-Kronecker Diagrams with Complemented Edges (PKDDCE), Linearly Transformed Binary Decision Diagrams (LTBDDs), Function-driven Decision Diagrams (fDDs) [39], or other similar diagrams. The goal of representing functions in such a representation is to find the “natural” structure of the function, helpful for its subsequent partitioning to blocks of logic and subsets of variables. Let us remind that in PKDD an expansion variable goes through an entire level of a diagram. Observe as well that a Toffoli gate uses Davio Expansion as one of its outputs and forwards two of its inputs to outputs. Therefore, a fast natural mapping from a PKDD or PKDDCE diagram to a reversible netlist with Toffoli gates exists. First a PKDD, PKDDCE, or other similar diagram is mapped to Feynman, Fredkin and Toffoli gates and inverters, in such a way that there is no feedback loops and no fan-out larger than one from primary inputs and gates. We will discuss the Toffoli gate mapping as an example, but we have created similar rules for Feynman, Fredkin and Kerntopf gates (the rules use also inverters). After the mapping, every Toffoli gate in the mapped

circuit can be in one of the following states: no garbage outputs, one garbage output, two garbage outputs. Thus, a group of Toffoli gates controlled by the same control variable can have some percentage p of garbage outputs. T_j are different values for various gate types. If this value p is higher than some threshold value T_j , the group is redesigned, otherwise it is retained. This is illustrated in Figures 3 and 4. The groups of Toffoli gates generated in this way create a partitioning of the initial circuit based on PKDD (PKDDCE) to blocks. Each of these blocks can be next redesigned using the MP decomposition. The redesign can be done separately for each block, or for groups of blocks. The value of T_j is selected experimentally. If the original function is not reversible, it is either made reversible using the approach from section 5 or the transformation to reversible logic circuit is achieved as a “byproduct” of finding a PKDD (PKDDCE) and next mapping to the diagram with

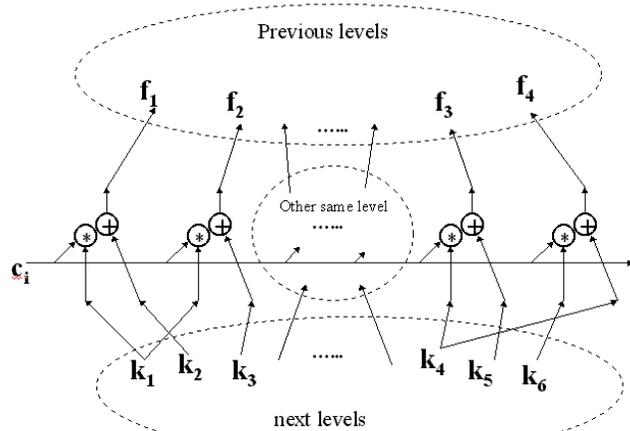


Figure 3. Part of PKDD with Positive Davio expansions in a level. Two typical patterns of connections that can be mapped to Toffoli gates with small garbage.

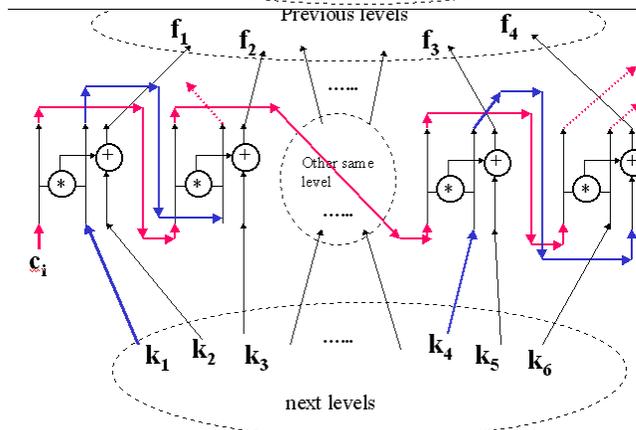


Figure 4. Part of PKDD from Figure 3 after mapping to Toffoli gates. This mapping determined natural partitioning to previous levels, next levels and other gates of this level. Garbage outputs are drawn in interrupted lines.

Toffoli, Feynman, Fredkin and inverter gates. The second approach may lead to a too large garbage. Preprocessing introduces also some bias towards Toffoli gates, but it is a necessary stage of synthesizing large multi-output functions.

Example 2. As an example, let us consider the two-output function $\langle f, g \rangle$ represented by PKDDCE from Figure 5a. Observe that there exist positive Davio (pD) and negative Davio (nD) nodes for variable d and Shannon nodes for other variables. There is also a complemented edge incoming to the nD node. Using the rules that extend those shown above, plus similar rules to map two Shannon nodes with common inputs to a Fredkin gate plus a rule of dealing with a node that corresponds to an input variable, the reversible circuit built from Toffoli, Fredkin and inverter gates is obtained after mapping (see Figure 5b). The groups of nodes corresponding to reversible gates and to variables in the diagram (Figure 5a) are marked by dotted lines. Observe the following properties: all signals (including primary inputs) have a fan-out equal to one, there are no loops, no wired connections, and all gates are reversible.

Thus the circuit is reversible. The garbage is 3 (garbage signals are denoted by G1, G2 and G3). Our circuit has one Fredkin gate, two Toffoli gates and three inverters. Inverters can be incorporated to the respective gates, creating “new standard cell gates”. This would lead to a solution with only three reversible gates and delay of two. Comparing to the circuit based on Sasao-Kinoshita cascade, our circuit produces smaller garbage and number of gates, despite that our circuit has two outputs, while the method from [67] allows only single-output functions, so their cascade should be additionally duplicated. Our circuit has also smaller delay. A comparison of the above circuit to the circuits based on Sum of Products and designed using

Picton's method [60] shows big advantage of using the PKDDCE mapping method. Symmetrizing function $f1$ and realizing it as a regular net structure with repeated variables from [56] would also lead to an inefficient circuit, because this function is hard to symmetrize. Finally, another naïve approach would be as follows: (1) to realize the circuit with two-input gates using any two-level or multi-level method of standard logic, (2) implement the two-input gates using inverters, Feynman, Fredkin, Toffoli or Kerntopf gates with constants substituted for some of their inputs. It is left to the reader to do this exercise, which should convince him how wasteful in terms of gates, delay and especially garbage, are all previous methods. In addition, one has to bear in mind that the PKDDCE mapping method is only a preprocessing, so that further transformations presented below are used to improve the initial solution based on the mapping alone.

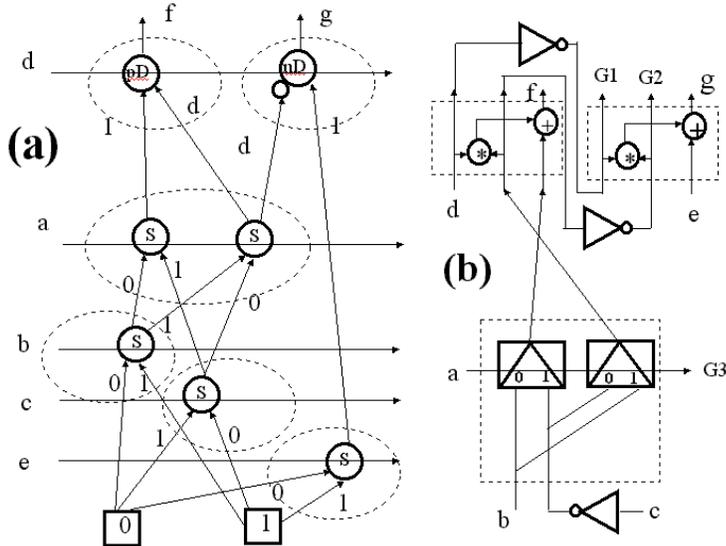


Figure 5. Mapping from PKDDE, (a) PKDDE with positive Davio and negative Davio nodes for variable d and inverted edge, (b) The corresponding circuit with Toffoli gates, inverters and a Fredkin gate obtained after transformation.

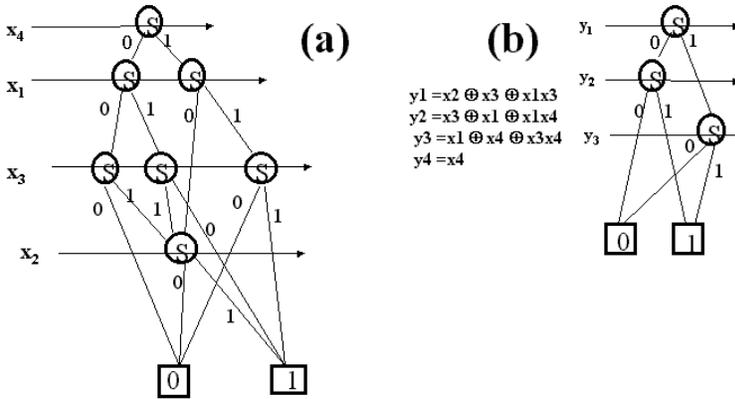


Fig. 6. Use of Function-driven Decision Diagrams, (a) original BDD for function h , (b) fDD of function h

Example 3. Additional advantages are obtained when we start from the Function-driven Decision Diagrams (fDDs) [39] or its special case, the Linearly Transformed Binary Decision Diagrams (LTBDDs). Figure 6a shows a standard BDD of function f . Figure 6b shows its counterpart fDD based on the following input preprocessing:

$$\begin{aligned}
 y_1 &= x_2 \oplus x_3 \oplus x_1 x_3 \\
 y_2 &= x_3 \oplus x_1 \oplus x_1 x_4 \\
 y_3 &= x_1 \oplus x_4 \oplus x_3 x_4 \\
 y_4 &= x_4
 \end{aligned}$$

The final reversible circuit after mapping is shown in Figure 7 (inverters for x_1 and x_4 were not drawn). It has one Fredkin gate (in its part corresponding to BDD on new variables), and four inverters, Feynman gate and three Toffoli gates in the inputs preprocessing circuit. Let us observe that the Feynman gate was used to obtain both the inverted variable and a variable

copy. The preprocessing circuit with negations only would be cyclic, which is not allowed for reversible logic, thus we used the solution with Feynman gate that does not lead to cyclicity of gates. Three garbage bits were generated.

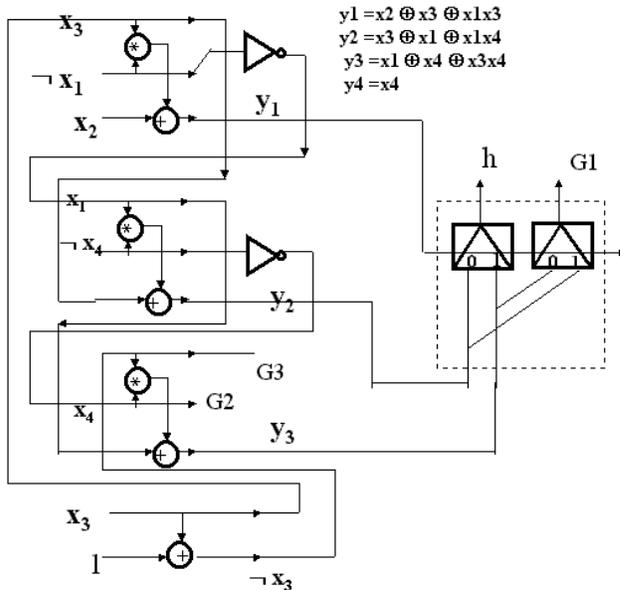


Figure 7. The reversible circuit corresponding to the fDD from Figure 6b.

4. Compositional Approach to Synthesis.

There exist basically two approaches to decomposition: (1) the well-known method of Ashenurst and Curtis (A/C decomposition, in short) [14] which can be characterized as **recursive top-down reduction** from outputs to inputs. (2) the **compositional approach** of Dietmeyer [20,21,42] which can be characterized as bottom-up (it starts from the primary inputs of the network, building intermediate levels, until all output functions are realized). This second approach has been developed in works of Dietmeyer and Schneider [20,70], Fang and Wojcik [25], Michalski [47], Jozwiak et al [30-37], Chojnacki et al [10,11], Rawski et al [63,64,65], Volf et al [73,74,75], and Kravets and Sakallah [43,44]. We want to emphasize here that the fundamental idea of Dietmeyer [21] should become a general-purpose decomposition paradigm, similarly to the already popular A/C paradigm. In contrast to the A/C decomposition, Dietmeyer's paradigm is particularly useful and **easy to adapt** for reversible logic. Although so far this method is less frequently used than the A/C decomposition, the programs developed for this approach has become prototypes of software created worldwide and influenced also the state of the art in industry, originally in IBM. Not only these programs were first to introduce the concept of **composition** rather than decomposition. They linked the synthesis to certain "gates" or "logic blocks" rather than to *arbitrary subfunctions* and they used the concepts of symmetry. Kim and Dietmeyer [42] observed that previous systems for multilevel synthesis from PLA-like macros led to poor results for symmetric functions. Designs of totally symmetric functions generated from descriptions that lack global network structure had on average more than twice as many literals as the best designs, while the designs of nonsymmetric functions had on average 20 % more literals than the best designs. Taking advantage of symmetry in multilevel synthesis requires detection of symmetry sets of multiple-output function F . Extensive work on the detection of symmetry sets was reported in [70]. Detecting of symmetry in multi-output functions may be performed by sequentially testing the cube arrays of each component output function f_i . The detection of symmetry pairs forms the basis for detecting larger symmetry sets. Iterative decomposition using the "**heuristic recoding technique**" is efficient and effective for totally symmetric functions. The authors wrote that expanding this approach for partially symmetric functions is an open problem, but they believe that many of their ideas will also work for such symmetric functions. They suggested to select the best recoder type based on the analysis of functions to be decomposed. Although usage of symmetry suggested by Dietmeyer et al. is not necessarily linked to compositional methods, it should give very good results for this approach, as suggested by subsequent results of Volf et al., Chojnacki et al., Jozwiak et al. and PSU group. It gave also very good results for the generalization of Curtis decomposition with small bound sets [28].

Now we will compare the advantages and disadvantages of the two above listed paradigms, especially from the point of view of using them for reversible logic. The A/C approach may require generating of all partitions, which is usually a very large number. Next, each partition matrix must be examined to determine if it possesses the specific decomposition property that is

being considered. Since only a very small number of functions will have a specific property [7] if the function does not have the desired property, the analysis does not yield a design. Hence the designer will have to consider alternative decompositions or select some other approach to design the function. Fang and Wojcik's [25] paper is an excellent reference to non-A/C decompositional approaches to synthesis. The disadvantage of the compositional method is its inherent strong bias towards selected gates. The method of Fang and Wojcik follows the approach of Dietmeyer [21], but it differs in several key respects. The principle idea is to develop a systematic procedure which attempts at function decomposition with modularity. It is a top-down approach which seeks to identify common subfunctions. The decomposition of the target function into subfunctions is considered in terms of available components, which constitute a functionally complete set. The set can be a collection of building blocks or a single universal building block such as a fixed-sized multiplexer, or a fixed-sized PLA. Thus this method is suitable for reversible logic with its relatively small set of multi-output blocks. The technique of Dietmeyer is based on using building blocks that are determined after a search of partition matrices for a classic decomposition property. If the decomposition does not exist, the set of building blocks would not be found. While in A/C approach a function is rewritten in terms of new variables (functions), Wojcik and Feng do not attempt to rewrite the function in terms of subfunctions which are next used as new variables in the function's logic equation. Rather, they identify which of the available components used to implement the subfunctions can be interconnected to represent the target function. The approach uses a predefined collection of modules that are used to design an arbitrary function. (Their approach was developed for MV functions of any radix but can be applied to binary functions as well.) This synthesis method has been developed along with several heuristic techniques to minimize the number of components used in the design. Furthermore, evaluation of the solution takes into account many criteria, such as the number of modules, the complexity of module interconnections, the number of logic levels in the design, etc. In the approach of Feng and Wojcik, the complex problem of identifying whether or not the function is decomposable is greatly simplified, since decomposition is considered only in terms of the available components. All functions can be decomposed using this approach and in the worst case, a canonical form of the function is generated, leading to a tree structure to implement the function. The compositional technique was applied to multiple-valued logic also by A. Michalski [47].

In a series of works [30-37,63,64,65,73,74,75] a new compositional approach has been introduced that uses concepts of general decomposition and composition schemes, partition-based formalisms and information theory measures. Paper [30] presents a "*theorem on General Decomposition*", and an explanation that all other decomposition structures are special cases of the general decomposition structure. A general decomposition methodology explaining how to apply the general decomposition scheme (theorem) that constitutes a correct circuit generator to effectively and efficiently construct circuits in the framework of a heuristic search was also given. Paper [31] presents methods for analyzing information and information relationships, and computing the amount of information and information relationship measures in (binary, multi-valued, symbolic etc.) functions, relations, sequential machines and *networks* of functions, relations, and sequential machines. Results of this analysis can be used in particular for controlling the bottom-up circuit construction by general functional (de)composition in the framework of the heuristic constructive search, i.e. can give data to make the particular circuit construction decisions. Recently, this approach has produced excellent results, reported in [35,36,37]. The detailed description of the latest tool IRMA2FPGAS (Information Relationships and Measures Applied to FPGA Synthesis) for bottom-up circuit synthesis with arbitrary multi-input, multi-output gates can be found there. Because this approach is applicable to *arbitrary multi-output modules*, it can be applied in particular to arbitrary reversible gates. We will not describe this approach here in more detail. Let us only observe that the software developed in [35,36,37] is already directly applicable to any reversible gates as sub-functions and the information theory measures can be easily adapted to reversible logic, possibly leading to design quality improvements. The only constraints are natural to reversible logic: *no feedback loops and no fan-out larger than 1*. In several small benchmark examples we found that the composition method works best with the following choice of gates: inverter, 2*2 Feynman, 3*3 Fredkin, Toffoli, and Kerntopf. Observe that each of these gates can be used also with any constants substituted for input signals, but in such a case the Kerntopf gate is the best choice, because it is the only one of them that can realize concurrently logic operators OR and AND, and in addition NAND and IMPLICATION with another choice of the controlling constant value [56]. The two-input AND/OR gate is very useful to realize symmetric and threshold functions [56,58].

Observe, that the general paradigm of "*synthesizing a multi-output function by sequential bottom-up composition of multi-output gates*" is a very general and powerful one. It can be realized *differently* than in any of the above-mentioned previous works [20,21,25,30-37,42,43,63,64,65,70,73,74,75] The cost differences in applying various variants can be quite dramatic even on small functions. We believe that compositional methods can become a very fruitful research area for applications in both binary and multi-valued reversible logic synthesis. And also to quantum logic synthesis with *arbitrary* reversible quantum gates. One of advantages of this approach is that it can easily incorporate layout, delay, test or other design constraints and can be combined with such methods as Genetic Algorithms, Genetic Programming, Simulated Annealing,

Tabu Search, or Array Genetic Algorithms. In this paper we will only show examples of compositional synthesis using reversible gates. The interested reader is referred to literature for details.

Toffoli				
A B C	X Y Z	h=A⊕B	g=A*B	G
0 0 0	0 0 0	0	0	-
0 0 1	0 0 1	0	0	-
0 1 0	0 1 0	1	0	-
0 1 1	0 1 1	1	0	-
1 0 0	1 0 0	1	0	-
1 0 1	1 0 1	1	0	-
1 1 0	1 1 1	0	1	-
1 1 1	1 1 0	0	1	-

$Z=A*B$

Figure 8. Step-by-step creation of truth table for half-adder. Intermediate variables X,Y,Z assume selection of Toffoli gate in the first level.

Example 4. Composition from inputs. In this example we will show the truth table representation for non-deterministic compositional method that selects an arbitrary reversible gate and creates new intermediate variables corresponding to the outputs of this gate. The method starts from the primary inputs. The heuristic is to select the gate that has the best match, it means the largest number of minterms in which the two variables are the same. We will design a half-adder, $g = A * B$, $h = A \oplus B$ (see Fig. 8). Given is a truth table of function $\langle g(A, B), h(A, B) \rangle$. Because this function is not reversible, we have to add one garbage output G and one input C that will be next set to a constant. Thus we have $\langle g(A, B, C), h(A, B, C), G(A, B, C) \rangle$. Assume Toffoli gate with ordered outputs X, Y, Z has been selected as a composing gate and applied to input variable order A, B, C as in Figure 8. Now we see in the truth table that $g = Z|_{C=0}$, which means function Z restricted to $C=0$. (The rows for which $C=0$ are boxed). Thus C is set to constant 0 and only half table will be considered from now. It is easy to see that now $h = X \oplus Y$. Feynman gate is thus selected to realize h from X, Y . The circuit from Figure 9 is obtained (we introduce here a new simplified notation for reversible gates). To help the reader analyze the solution, the equations of the signals are written near them. The advantage of this method is that it is not able to produce circuits with loops or fan-outs larger than one (so every solution is correct and does not require to be verified, which is the case for most other algorithms). This method is also easier to implement in a program.

5. Forward and Backward Synthesis Modes

It is a well known fact and easy to verify by the reader, that Fredkin, Toffoli, Feynman and Inverter are their own inverses, which means that cascade of two repeated gates of the same type (without permuting of signals) creates an identity function. For instance, for Toffoli gate the property can be described symbolically as follows: $TOFFOLI * TOFFOLI^{-1} = I$, $TOFFOLI = TOFFOLI^{-1}$. It can be observed, however, that Kerntopf gate is not equal to its own inverse. The inverse to Kerntopf gate, denoted $KERNTOPF^{-1}$ is described by equations: $A = Q \oplus PR$, $B = \neg PQ \oplus \neg R$, $C = \neg RP \oplus R \neg Q$. Observe, that although these equations are not the same as for Kerntopf gate, although they are of the same type, i.e., two of

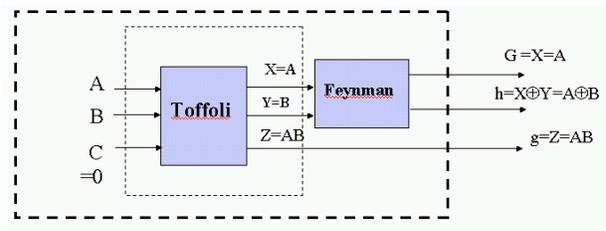


Figure 9. Circuit corresponding to synthesis procedure from Example 4. Dotted lines show stages of creating subfunctions.

them are NP-equivalents of Davio operator and one is NP-equivalent of Shannon operator. Knowledge of such properties is useful in the selection process of sub-functions in the composition methods. Finding the entire inversed functions is also very useful in synthesis. For instance, let us observe a very interesting property of reversible logic – *any synthesis algorithm for*

reversible logic can be applied both in standard, forward, way, in which output signals are functions of input signals, and in a reverse way, in which input signals are functions of output signals (*Kmap inverted*). Because of reversibility of a multi-output function F that we want to decompose, one can find a specification of function F^{-1} being an inverse of F , apply the input decomposition to it, and next find the structure from inverse modules, in which output pins of every gate are replaced with input pins. This approach is functionally equivalent to decomposing a function from outputs to inputs. Let us observe that this property of “*synthesis from a reverse specification*” does not exist for standard logic, and is a **unique property of reversible logic**, which makes the compositional synthesis methods especially attractive. Such approach may lead to better results than the straightforward synthesis of function F (similarly as it is useful to search a graph heuristically both forward and backwards, when the resources are limited). This methodology can be used to extend **any synthesis method for reversible logic** to operate in two directions: **forward and backwards**. Because we never know which direction will give better results, **any algorithm presented below can be applied twice**, one in each direction, and the better result can be selected. If a multi-output function is not reversible, it can be completed to a reversible function using one of the known methods based on successive adding of primary inputs and primary outputs. Although the above described property directly results from the definition of reversible logic, amazingly it was not observed in the literature as a synthesis method. It can be also applied to bi-directional search for the best circuit (such type of search is known for its efficiency in some AI problems).

Function F		Function F ⁻¹	
ABCD	XYZV	XYZV	ABCD
0000	0011	0000	0100
0001	1011	0001	0110
0010	0010	0010	0010
0011	1010	0011	0000
0100	0000	0100	1111
0101	0111	0101	1101
0110	0001	0110	0111
0111	0110	0111	0101
1000	1111	1000	1001
1001	1000	1001	1011
1010	1110	1010	0011
1011	1001	1011	0001
1100	1101	1100	1110
1101	0101	1101	1100
1110	1100	1110	1010
1111	0100	1111	1000

(a)
(b)

Figure 10. Truth tables of reversible functions, (a) for function F_4 , (b) for function F_4^{-1} . Observe that both truth functions are all permutations of 4-bit binary vectors.

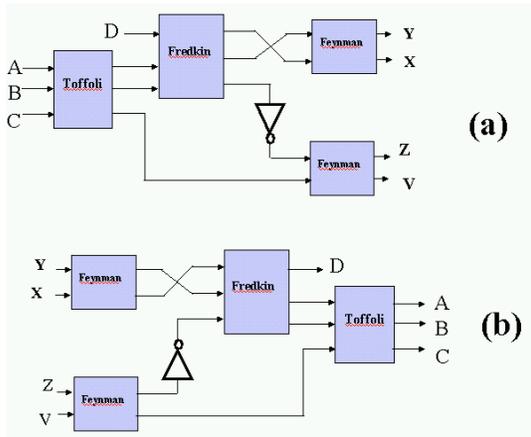
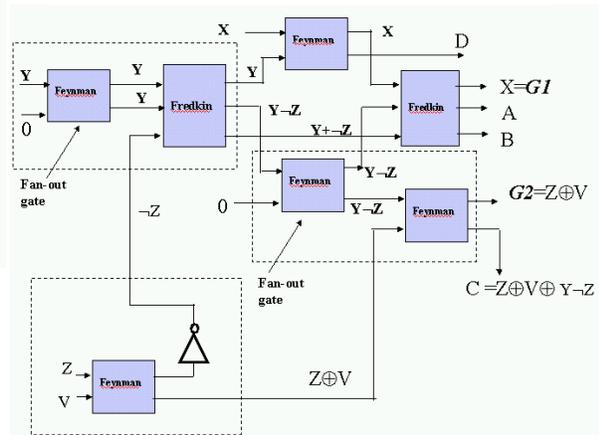


Figure 11. (a) Circuit of function F_4 , (b) circuit for function F_4^{-1} , which is a mirror circuit of the circuit from Fig. 11a.

Figure 12. Another realization of function F_4^{-1} . Observe that only Feynman and Fredkin gates are used.



Example 5. In Figure 10a given is a truth table of function F_4 . Applying the composition method the circuit from Figure 11a is found. The truth table of function F_4^{-1} , inverse to F_4 , is generated from the truth table of function F_4 . Inverse to function F_4 , it is shown in Figure 10b. The circuit corresponding to F_4^{-1} is shown in Figure 11b. Observe that the delay is 4 levels of logic for outputs A, B, C and two levels of logic for output D . Observe also, that this circuit is a mirror of circuit F_4 . By cascading circuits F_4 and F_4^{-1} we obtain an identity circuit (four horizontal wires A, B, C, D). Using outlined methods, the

function $F4^{-1}$ is synthesized again, Figure 12. Observe, that in this version two constant inputs and two garbage outputs $G1$ and $G2$ are added and the delay is increased. However, it was assumed here to use only Fredkin gates (because Toffoli gates have been not built in some technologies, or because Fredkin gates are simpler or faster in other technologies). This circuit illustrates also the possibility of post-logic-synthesis circuit transformation to improve speed. To help the reader analyze this solution, equations were written for signals. This way, it is seen that $D = X \oplus Y$ so the circuit can be redesigned (adding more fan-out gates) to have a delay of one for output D . Observe also, that each group of gates inside an dotted-line box can be combined to a single gate. These are only some examples of rule-based “technology mapping” transformations executed on the circuit, that take reversible logic properties into account. This stage of post-processing follows MP decomposition and is not discussed in this paper. We illustrated also techniques of creating fan-out greater than one using Feynman gate and creating simple two-input gates using Fredkin gates, which are the “last-resort” methods, that can be applied when a better solution cannot be found by searching and matching (de)composition methods. This circuit illustrates also the fundamental property that we pay for each additional constant with one garbage output, so adding constants should be avoided. However, finding a circuit without constants (see Figure 11b), is often very difficult and requires an extensive search. Because of branching properties of DAGs of circuits, searching from backwards can be sometimes simpler (for a given library of cells) than searching forwards. Having only cells that are their own inverses, or having the cells and their reverses in library would not require both searches, but would increase the search space. All these issues should be investigated experimentally. Finding circuits from Figs. 11 and 12 is left as an exercise to the Reader. Any of the presented above method should give these results.

6. Reversible Output Decomposition Mode

The (non-deterministic) procedure of the Output Decomposition type for a multi-output function is the following:

- (1) Create set of available signals AS, initialize it to all primary outputs.
- (2) Take any k signals (other than primary inputs, including, possibly, also garbage outputs),
- (3) Select an $k * k$ reversible gate G and link the outputs of this gate to these signals.
From the reversibility property of this gate calculate the functions realized by the k inputs of gate G. In a general case of arbitrary reversible gate, it can be done using BDDs or matrix calculus methods in case of quantum logic.
- (4) Add the input signals of G (other than constants) to AS and remove the output signals of G from AS.
- (5) Iterate (2) – (4) until AS becomes an empty set.

Example 6. Simple example circuit (half-adder) for composition and decomposition methods is shown in Figure 13.

METHOD 1. Reversible Decomposition method, from outputs to inputs. Given are output functions $g = AB$ and $h = A \oplus B$. These two outputs are taken and a $2*2$ Feynman gate is applied to them as the output module. This creates intermediate two new functions $Q = AB$ and $P = A+B$ on inputs of this gate. It is directly recognized from module library that these both functions can be realized by a Kerntopf gate with inputs A, B, C and with its input $C = I$. One garbage output $\neg B$ is created. As we see, in this example, the original multi-output function $\langle g, h \rangle$ is completed to reversible function $\langle f, g, \neg B \rangle$ of arguments $\langle A, B, C=I \rangle$ as a “byproduct” of the synthesis process.

METHOD 2. Composition method, from inputs to outputs. Inputs A and B are taken. Various gates are matches in order to select a gate that has the smallest difference with the desired outputs. The Kerntopf gate with $C=I$ is selected to create functions $Q = AB$ (which is the required output) and $P=A+B$ (which is a function with small difference to other required output $A \oplus B$). Representations of intermediate functions P, Q and R in terms of input variables $A, B, C=I$ are calculated and inserted to the data base of available functions. Applying Feynman gate to Q and P creates functions AB and $A \oplus B$, which are primary output functions, so the procedure is completed. Signal $R = \neg B$ is not used so it makes as a garbage output. This result is optimal, since the number of gates and garbage/constant inputs cannot be reduced.

METHOD 3. Decomposition method, from outputs to inputs of an inverse function. Because function of a half-adder is not reversible (as seen in Figure 14a), it is first completed to a reversible function from Figure 14c,d (completion of a function to a reversible function requires usually adding both inputs and outputs and is not a unique operation). Next from reversible function $\langle R(A,B,C), P(A,B,C), Q(A,B,C) \rangle$ its inverse function is calculated as $\langle A(R,P,Q), B(R,P,Q), C(R,P,Q) \rangle$, using Boolean equation or BDD methods. To this new function METHOD 1 is applied and a schematic is drawn. Next, all inputs and outputs in the schematic are inversed and the functions of blocks are replaced with their inverse functions.